

## ONLINE APPENDIX

**Online Appendix Mplus Syntax, to accompany: Sterba, S.K. (2017). Pattern mixture models for quantifying missing-data uncertainty in longitudinal invariance testing. *Structural Equation Modeling*, 24, 283-300.**

The online appendix provides syntax for a Conventional Longitudinal Factor Model (LFM) and a Pattern Mixture Longitudinal Factor Model (PM-LFM, using each identifying constraint option (1)-(5) from the manuscript). For illustration, syntax is shown for T=3, J=4 (and G=3, for PM-LFM). For illustration, weak longitudinal measurement invariance (MI) is imposed for these models.

### **Conventional Longitudinal Factor Model (LFM): Imposing weak longitudinal MI**

```
DATA: FILE = yourdata.dat;
VARIABLE: NAMES = y1-y12;
USEVARIABLES = y1-y12 ;
MISSING = .;
ANALYSIS: ESTIMATOR = ML;
MODEL:
f1 BY y1-y4*(I1-I4);
f2 BY y5-y8*(I1-I4);
f3 BY y9-y12*(I1-I4);
y1-y12*;
[y1@0]; [y2-y4*];
[y5@0]; [y6-y8*];
[y9@0]; [y10-y12*];
[f1-f3*];
f1-f3@1;
f1 WITH f2; f2 WITH f3; f1 WITH f3;
```

### **Pattern Mixture Longitudinal Factor Model (PM-LFM): Imposing weak longitudinal MI**

```
DATA: FILE = yourdata.dat;
VARIABLE: NAMES = y1-y12 GROUP;
USEVARIABLES = y1-y12 ;
MISSING = .;
GROUPING IS GROUP(1=complete 2=dropt2 3=dropt3);
ANALYSIS: ESTIMATOR = ML;

MODEL: !specification for group dropt3
f1 BY y1* (I1g3)
      y2 (I2g3)
      y3 (I3g3)
      y4 (I4g3);
f2 BY y5* (I5g3)
      y6 (I6g3)
      y7 (I7g3)
      y8 (I8g3);
f3 BY y9* (I9g3)
      y10 (I10g3)
      y11 (I11g3)
      y12 (I12g3);
```

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y1 (t1g3); y2 (t2g3); y3 (t3g3); y4 (t4g3);  
y5 (t5g3); y6 (t6g3); y7 (t7g3); y8 (t8g3);  
y9 (t9g3); y10 (t10g3); y11 (t11g3); y12 (t12g3);  
[y1@0]; [y2] (v2g3); [y3] (v3g3); [y4] (v4g3);  
[y5@0]; [y6] (v6g3); [y7] (v7g3); [y8] (v8g3);  
[y9@0]; [y10] (v10g3); [y11] (v11g3); [y12] (v12g3);  
[f1] (completemf1); [f2] (completemf2); [f3] (completemf3); f1-f3@1;  
f1 with f2 (completef12); f2 with f3 (completef23); f1 with f3 (completef13);

MODEL COMPLETE: !specification for group complete

f1 by y1\* (l1g1)

y2 (l2g1)

y3 (l3g1)

y4 (l4g1);

f2 by y5\* (l5g1)

y6 (l6g1)

y7 (l7g1)

y8 (l8g1);

f3 by y9\* (l9g1)

y10 (l10g1)

y11 (l11g1)

y12 (l12g1);

y1 (t1g1); y2 (t2g1); y3 (t3g1); y4 (t4g1);

y5 (t5g1); y6 (t6g1); y7 (t7g1); y8 (t8g1);

y9 (t9g1); y10 (t10g1); y11 (t11g1); y12 (t12g1);

[y1@0]; [y2] (v2g1); [y3] (v3g1); [y4] (v4g1);

[y5@0]; [y6] (v6g1); [y7] (v7g1); [y8] (v8g1);

[y9@0]; [y10] (v10g1); [y11] (v11g1); [y12] (v12g1);

[f1] (completemf1); [f2] (completemf2); [f3] (completemf3); f1-f3@1;

f1 with f2 (completef12); f2 with f3 (completef23); f1 with f3 (completef13);

MODEL DROPT2: !specification for group dropt2

f1 by y1\* (l1g2)

y2 (l2g2)

y3 (l3g2)

y4 (l4g2);

f2 by y5\* (l5g2)

y6 (l6g2)

y7 (l7g2)

y8 (l8g2);

f3 by y9\* (l9g2)

y10 (l10g2)

y11 (l11g2)

y12 (l12g2);

y1 (t1g2); y2 (t2g2); y3 (t3g2); y4 (t4g2);

y5 (t5g2); y6 (t6g2); y7 (t7g2); y8 (t8g2);

y9 (t9g2); y10 (t10g2); y11 (t11g2); y12 (t12g2);

[y1@0]; [y2] (v2g2); [y3] (v3g2); [y4] (v4g2);

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```
[y5@0]; [y6] (v6g2); [y7] (v7g2); [y8] (v8g2);  
[y9@0]; [y10] (v10g2); [y11] (v11g2); [y12] (v12g2);  
[f1] (completemf1); [f2] (completemf2); [f3] (completemf3); f1-f3@1;  
f1 with f2* (completef12); f2 with f3* (completef23); f1 with f3* (completef13);
```

### MODEL CONSTRAINT:

```
new (pg1 pg2 pg3 l1-l12 t1-t12 v1-v12);  
! insert observed proportions of dropout-pattern-group membership  
pg1=.6453333333;  
pg2=.1773333333;  
pg3=.1773333333;
```

### *! Computing marginal (across-missingness-pattern) parameters*

```
l1=l1g1*pg1+l1g2*pg2+l1g3*pg3;  
l2=l2g1*pg1+l2g2*pg2+l2g3*pg3;  
l3=l3g1*pg1+l3g2*pg2+l3g3*pg3;  
l4=l4g1*pg1+l4g2*pg2+l4g3*pg3;  
l5=l5g1*pg1+l5g2*pg2+l5g3*pg3;  
l6=l6g1*pg1+l6g2*pg2+l6g3*pg3;  
l7=l7g1*pg1+l7g2*pg2+l7g3*pg3;  
l8=l8g1*pg1+l8g2*pg2+l8g3*pg3;  
l9=l9g1*pg1+l9g2*pg2+l9g3*pg3;  
l10=l10g1*pg1+l10g2*pg2+l10g3*pg3;  
l11=l11g1*pg1+l11g2*pg2+l11g3*pg3;  
l12=l12g1*pg1+l12g2*pg2+l12g3*pg3;  
  
t1=t1g1*pg1+t1g2*pg2+t1g3*pg3;  
t2=t2g1*pg1+t2g2*pg2+t2g3*pg3;  
t3=t3g1*pg1+t3g2*pg2+t3g3*pg3;  
t4=t4g1*pg1+t4g2*pg2+t4g3*pg3;  
t5=t5g1*pg1+t5g2*pg2+t5g3*pg3;  
t6=t6g1*pg1+t6g2*pg2+t6g3*pg3;  
t7=t7g1*pg1+t7g2*pg2+t7g3*pg3;  
t8=t8g1*pg1+t8g2*pg2+t8g3*pg3;  
t9=t9g1*pg1+t9g2*pg2+t9g3*pg3;  
t10=t10g1*pg1+t10g2*pg2+t10g3*pg3;  
t11=t11g1*pg1+t11g2*pg2+t11g3*pg3;  
t12=t12g1*pg1+t12g2*pg2+t12g3*pg3;  
  
v1=0;  
v2=v2g1*pg1+v2g2*pg2+v2g3*pg3;  
v3=v3g1*pg1+v3g2*pg2+v3g3*pg3;  
v4=v4g1*pg1+v4g2*pg2+v4g3*pg3;  
v5=0;  
v6=v6g1*pg1+v6g2*pg2+v6g3*pg3;  
v7=v7g1*pg1+v7g2*pg2+v7g3*pg3;  
v8=v8g1*pg1+v8g2*pg2+v8g3*pg3;  
v9=0;  
v10=v10g1*pg1+v10g2*pg2+v10g3*pg3;
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$$v_{11} = v_{11g1} * pg_1 + v_{11g2} * pg_2 + v_{11g3} * pg_3;$$

$$v_{12} = v_{12g1} * pg_1 + v_{12g2} * pg_2 + v_{12g3} * pg_3;$$

*limposing weak longitudinal MI on marginal loadings*

*lto relax weak longitudinal MI delete these 8 constraints*

*L1=L5; L2=L6; L3=L7; L4=L8; L5=L9; L6=L10; L7=L11; L8=L12;*

### Additional PM-LFM model constraints to be included depending on chosen identification method

<u>Nearest Neighbor (NN) identifying constraints</u>	<u>Complete Case (CC) identifying constraints</u>	<u>Available Case (AC) identifying constraints</u>	<u>Last observation carried forward (LOCF) identifying constraints</u>	<u>Nearest Neighbor Difference (NND) identifying constraints</u>
l5g2=l5g3; l6g2=l6g3; l7g2=l7g3; l8g2=l8g3; l9g2=l9g3; l10g2=l10g3; l11g2=l11g3; l12g2=l12g3; t5g2=t5g3; t6g2=t6g3; t7g2=t7g3; t8g2=t8g3; t9g2=t9g3; t10g2=t10g3; t11g2=t11g3; t12g2=t12g3; v6g2=v6g3; v7g2=v7g3; v8g2=v8g3; v10g2=v10g3; v11g2=v11g3; v12g2=v12g3;  l9g3=l9g1; l10g3=l10g1; l11g3=l11g1; l12g3=l12g1; t9g3=t9g1; t10g3=t10g1; t11g3=t11g1; t12g3=t12g1; v10g3=v10g1; v11g3=v11g1; v12g3=v12g1;	l5g2=l5g1; l6g2=l6g1; l7g2=l7g1; l8g2=l8g1; l9g2=l9g1; l10g2=l10g1; l11g2=l11g1; l12g2=l12g1; t5g2=t5g1; t6g2=t6g1; t7g2=t7g1; t8g2=t8g1; t9g2=t9g1; t10g2=t10g1; t11g2=t11g1; t12g2=t12g1; v6g2=v6g1; v7g2=v7g1; v8g2=v8g1; v10g2=v10g1; v11g2=v11g1; v12g2=v12g1;	l5g2=pg3*l5g3+pg1*l5g1; l6g2=pg3*l6g3+pg1*l6g1; l7g2=pg3*l7g3+pg1*l7g1; l8g2=pg3*l8g3+pg1*l8g1; l9g2=l9g3; l10g2=l10g3; l11g2=l11g3; l12g2=l12g3; t5g2=pg3*t5g3+pg1*t5g1; t6g2=pg3*t6g3+pg1*t6g1; t7g2=pg3*t7g3+pg1*t7g1; t8g2=pg3*t8g3+pg1*t8g1; t9g2=t9g3; t10g2=t10g3; t11g2=t11g3; t12g2=t12g3; v6g2=pg3*v6g3+pg1*v6g1; v7g2=pg3*v7g3+pg1*v7g1; v8g2=pg3*v8g3+pg1*v8g1; v10g2=v10g3; v11g2=v11g3; v12g2=v12g3;	l5g2=l1g2; l6g2=l2g2; l7g2=l3g2; l8g2=l4g2; l9g2=l1g2; l10g2=l2g2; l11g2=l3g2; l12g2=l4g2; t5g2=t1g2; t6g2=t2g2; t7g2=t3g2; t8g2=t4g2; t9g2=t1g2; t10g2=t2g2; t11g2=t3g2; t12g2=t4g2; v6g2=v2g2; v7g2=v3g2; v8g2=v4g2; v10g2=v2g2; v11g2=v3g2; v12g2=v4g2;	l5g2=l1g2-(L1G3-L5G3); l6g2=l2g2-(L2G3-L6G3); l7g2=l3g2-(L3G3-L7G3); l8g2=l4g2-(L4G3-L8G3); l9g2=l5g2-(L5G1-L9G1); l10g2=l6g2-(L6G1-L10G1); l11g2=l7g2-(L7G1-L11G1); l12g2=l8g2-(L8G1-L12G1); t5g2=t1g2-(T1G3-T5G3); t6g2=t2g2-(T2G3-T6G3); t7g2=t3g2-(T3G3-T7G3); t8g2=t4g2-(T4G3-T8G3); t9g2=t5g2-(T5G1-T9G1); t10g2=t6g2-(T6G1-T10G1); t11g2=t7g2-(T7G1-T11G1); t12g2=t8g2-(T8G1-T12G1); v6g2=v2g2-(V2G3-V6G3); v7g2=v3g2-(V3G3-V7G3); v8g2=v4g2-(V4G3-V8G3); v10g2=v6g2-(V6G1-V10G1); v11g2=v7g2-(V7G1-V11G1); v12g2=v8g2-(V8G1-V12G1);